

ABSTRACT OF THE DISCLOSURE

In a method and a device for assisting an operator of a vehicle in the vehicle stabilization, an additional steering torque is applied to the steering line of the vehicle.

The method manifests itself by the feature that a first component of the additional steering torque is determined depending on a steering angle difference between an instantaneous steering angle at steerable wheels of the vehicle and a nominal steering angle, and the steering angle difference is determined depending on a difference between an instantaneous value of a yaw rate of the vehicle and a value of a reference yaw rate, and with the value of the reference yaw rate being established in a vehicle model by way of a value of at least one variable predefined by the driver.

The device implements the method.